A Novel Divide-and-Conquer Model for CPI Prediction Using ARIMA, Gray Model and BPNN

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Research Background

- ✓ The Consumer Price Index (CPI) is a widely used measurement of cost of living
- ✓ Predicting the change of CPI is significant to both the public and policy makers





Research Background

- ✓ CPI consists of eight sub-indexes:
 - 1. Food
 - 2. Articles for Smoking and Drinking
 - 3. Clothing
 - 4. Household Facilities, Articles and Maintenance Services
 - 5. Health Care and Personal Articles
 - 6. Transportation and Communication
 - 7. Recreation, Education and Cultural Articles and Services
 - 8. Residence

Index	No.1	No.2	No.3	No.4	No.5	No.6	No.7	No.8
Weight	31.79%	3.49%	8.52%	5.64%	9.64%	9.95%	13.75%	17.22%

✓ The eight sub-CPIs are integrated with a specific formula as follow to form the value of CPI.

$$TI = \sum_{i=1}^{8} W_i I_i$$



GM(1,1)

The grey system theory is first presented by Deng in 1980s. In the grey forecasting model, the time series can be predicted accurately even with a small sample by directly estimating the interrelation of data. In this theory, a system in which information is completely known is defined as a white system while the system in which information is partly known is named a black box.

The GM (1, 1) model is one type of the grey forecasting which is widely adopted. It is a differential equation model of which the order is 1 and the number of variable is 1, too. The differential equation is:

$$\frac{dx^{(1)}}{dt} + ax^{(1)} = u$$

 $x^{(1)}$ is a sequence generated after accumulating, t is time, a and u are parameters to be estimated.





GM(1,1)

The process of GM (1, 1) model is represented in the following steps:

Step1: The original sequence is

$$x^{(0)} = \{x^{(0)}(1), x^{(0)}(2), x^{(0)}(3), \dots, x^{(0)}(n)\}, i = 1, 2, \dots, n$$

$$x^{(1)}(i) = \sum_{m=1}^{i} x^{(0)}(m),$$

 $i = 1, 2, \dots, n$

Step3: Equation solving

$$\hat{x}^{(1)}(i+1) = (x^{(0)}(1) - \frac{u}{a})e^{-ai} + \frac{u}{a},$$

$$\begin{cases} \hat{x}^{(0)}(1) = \hat{x}^{(1)}(1) \\ \hat{x}^{(0)}(i) = \hat{x}^{(1)}(i) - \hat{x}^{(1)}(i-1), i = 2, 3, \dots, n \end{cases}$$

Step2: Estimate the parameters a, u using the ordinary least square(OLS)

$$B = \begin{bmatrix} -\frac{1}{2} [x^{(1)}(1) + x^{(1)}(2)] & 1\\ -\frac{1}{2} [x^{(1)}(2) + x^{(1)}(3)] & 1\\ \vdots & \vdots\\ -\frac{1}{2} [x^{(1)}(n-1) + x^{(1)}(n)] & 1 \end{bmatrix}$$

$$y_n = [x^{(0)}(2), x^{(0)}(3), \dots, x^{(0)}(n)]^T$$

$$a \cdot u : \hat{a} = \begin{bmatrix} a \\ u \end{bmatrix} = (B^T B)^{-1} B^T y_n$$

Step4: Test the model using the variance ratio and small error possibility.



ARIMA

ARIMA model was first put forward by Box and Jenkins in 1970; therefore, it is also called" Box-Jenkins" model. ARIMA stands for "Autoregressive Integrated Moving Average." The model has been well acknowledged as a foremost method to forecast the future trend of a time series by taking full advantage of time series data in the past and present. ARIMA model is usually described as ARIMA (p, d, q), p refers to the order of the autoregressive variable, while d and q refer to integrated, and moving average parts of the model respectively. When one of the three parameters is zero, the model is changed to model "AR", "MR" or "ARMR". When none of the three parameters is zero, the model is given by:

$$(1 - \sum_{i=1}^{p} \phi_i L^i)(1 - L)^d X_t = \delta + (1 + \sum_{i=1}^{q} \theta_i L^i)\varepsilon_t$$

Where L is the lag number, \mathcal{E}_t is the error term.





ARIMA

The steps of ARIMA model are:

Step1: Test the Stationarity of the time series

Step2: Build the Model by the Regulations

Step3: White Noise Test

Step4: Analyzing and Forecasting

The constructed model is:

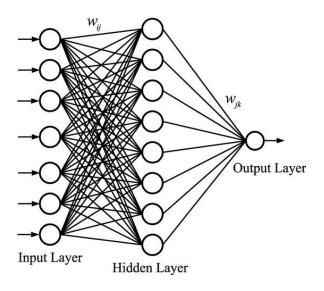
$$(1 - \sum_{i=1}^{p} \phi_{i} L^{i})(1 - L)^{d} X_{t} = \delta + (1 + \sum_{i=1}^{q} \theta_{i} L^{i}) \varepsilon_{t}$$

Where L is the lag number, \mathcal{E}_t is the error term.



BPNN

Artificial Neural Network (ANN) is a mathematical and computational model which imitates the operation of neural networks of human brain. ANN consists of several layers of neurons. Neurons of contiguous layers are connected with each other. The values of connections between neurons are called 'weight'. Back Propagation Neural Network (BPNN) is one of the most widely employed neural network among various types of ANN. BPNN was put forward by David Rumelhart and J.McClelland in 1985. It is a common supervised learning network well suited for prediction. BPNN consists of three parts, one input layer, several hidden layers and one output layer, as is demonstrated in Figure 1. The learning process of BPNN is modifying the weights of connections between neurons based on the deviation between the actual output and the target output until the overall error is in the acceptable range.



Back-propagation Neural Network



The Proposed Method

 monthly total CPI data Step1:Data collection monthly sub-CPIs data · eight sub-CPIs(food, clothing and so on) Step2:Decompose the · determine the decomposition formula total CPI into sub-CPIs • GM(1, 1) model Step3:Construction of ARIMA model three models BPNN model · obtain the forecasting results of sub-CPIs using the three models mentioned above Step4:Forecast the sub- choose the best forecasting model for each CPIs sub-CPI Step5:Calculate the total integrate the best forecasting results of 8 sub-CPIs to form the prediction of total CPI

CPI

The decomposition formula in step 2 and step 5 is:

$$Y = \sum_{i=1}^{8} c_i x_i$$

Where Y refers to the predicted rate of the total CPI, c_i is the weight of the sub-CPI which will be showed in table 1 and x_i is the predicted value of the sub-CPI which has the minimum error among the three models mentioned above.

Figure 1.The Framework of the dividing-conquer model

with the decomposition formula in Step2



Experimental Results

We construct the tree introduced models and get the experimental results as follows (take the Residence sub-CPI as example):

Table 2.

Forecasting results of Residence CPI by GM(1,1)

Date	Actual value	Predicted value	Residual error	Relative error
2013-4	102.9	103.0619	-0.1619	0.0016
2013-5	103.0	103.1621	-0.1621	0.0016
2013-6	103.1	103.2624	-0.1624	0.0016
2013-7	102.8	103.3628	-0.5628	0.0055
2013-8	102.6	103.4632	-0.8632	0.0084
2013-9	102.6	103.5638	-0.9638	0.0094

Table 4.
Forecasting results of Residence CPI by BPNN

Date	Actual value	Predicted value	Residual error	Relative error
2013-4	102.9	102.869784	0.030216	0.000294
2013-5	103.0	102.870656	0.129344	0.001256
2013-6	103.1	102.866411	0.233589	0.002266
2013-7	102.8	102.865677	-0.065677	0.000639
2013-8	102.6	102.864506	-0.264506	0.002578
2013-9	102.6	102.872821	-0.272821	0.002659

Table 3.
Forecasting results of Residence CPI by ARIMA

Date	Actual value	Predicted value	Residual error	Relative error
2013-4	102.9	102.8817	0.0183	0.0002
2013-5	103.0	102.7096	0.2904	0.0028
2013-6	103.1	102.8695	0.2305	0.0022
2013-7	102.8	103.0393	0.2393	0.0023
2013-8	102.6	102.7573	0.1573	0.0015
2013-9	102.6	102.5265	0.0735	0.0007

Table 5.

GM(1,1) 0.0378 0.0009 0.0075 0.0031 0.0010 0.0047 0.0061 0.0	Error of Sub-CPIs of the 3 Models									
	No.8	No.7	No.6	No.5	No.4	No.3	No.2	No.1		
4RIM4 0.0059 0.0025 0.0028 0.0016 0.0010 0.0072 0.0026 0.00	0.0047	47 0 0061	0.0047	0.0010	0.0031	0.0075	0,0009	0.0378	GM(1,1)	
Military 0.0025 0.0020 0.0010 0.0012 0.0020 0.0	0.0016	72 0.0026	0.0072	0.0010	0.0016	0.0028	0.0025	0.0059	ARIMA	
BPNN 0.0110 0.0193 0.0041 0.0036 0.0058 0.0053 0.0029 0.0	0.0016	53 0.0029	8 0.0053	0.0058	0.0036	0.0041	0.0193	0.0110	BPNN	



Experimental Results

- ✓ We re-model the forecasting approach for sub-index 1 and sub-index 6
- ✓ For predicting sub-index 1, we use BPNN for prediction based on first-order difference series of sub-index 1
- ✓ We offer MA model for predicting sub-index 6

The improved dividing-integration model

	No.1	No.2	No.3	No.4	No.5	No.6	No.7	No.8
Model	BPNN	GM(1,1)	ARIMA	ARIMA	GM(1,1)	MA	ARIMA	BPNN
Error	0.0028	0.0009	0.0027	0.0016	0.0010	0.0039	0.0026	0.0016

After calculating, the forecasting error of the total CPI by the improved dividing-integration model is 0.0023



Comparison

The original dividing-integration model

	No.1	No.2	No.3	No.4	No.5	No.6	No.7	No.8
Model	ARIMA	GM(1,1)	ARIMA	ARIMA	GM(1,1)	GM(1,1)	ARIMA	BPNN
Error	0.0059	0.0009	0.0028	0.0016	0.0010	0.0047	0.0026	0.0016

After calculating, the forecasting error of the total CPI by the original dividing-integration model is 0.0034

The baseline models

Model	SARIMA	BRF NN	Verhulst	ARIMA	GM(1,1)	VAR	
Error	0.0038	0.0057	0.0035	0.0038	0.0090	0.0179	



Conclusions

- ✓ In this paper, the prediction of national CPI is transformed into the forecasting of 8 sub-CPIs
- ✓ In the prediction of 8 sub-CPIs, we adopt three widely used models: a GM (1, 1) model, a ARIMA model and a BPNN model, we can obtain the best forecasting results for each sub-CPI
- ✓ We adjust the forecasting methods of sub-CPIs which predicting results are not satisfying enough and get the improved prediction results
- ✓ The improved predicting results of the 8 sub-CPIs are integrated to form the forecasting results of the total CPI





Future Work

✓ The proposed model only uses the time-series information of the CPI, and some factors can be considered to improve the accuracy and stability of the model, especially web information, such as web article news, and micro-blogging data.

✓ The forecasting performance of sub-CPIs can be improved by some new methods, such as SVM and DWD to deal with high dimension -small sample datasets





Thanks for your attention!